

APPROXIMATE SYSTEM RELIABILITY ANALYSIS OF DISTRIBUTION NETWORKS WITH REPAIRABLE COMPONENTS AND COMMON CAUSE FAILURES

By

D. RAVI KUMAR *

V. SANKAR **

* Assistant Professor, Department of Electrical Engineering, VNR Vignana Jyothi Institute of Engineering and Technology, Hyderabad, India.

** Professor, Department of Electrical Engineering, Jawaharlal Nehru Technological University, Anantapur, India.

ABSTRACT

Common Cause Failures (CCF) would indicate the failures of multiple components in a system due to some cause. In this paper, an attempt has been made to analyze the Limiting State Probabilities (LSP) of states for small repairable systems in which, the components are prone for failures due to CCF. For large systems, the same can also be used, as failure modes represent cut sets of the system and it is known that cut sets of order more than three can be ignored as they don't contribute much to predict the indices for approximate system reliability analysis. Analysis of repairable components with CCF is presented with a case study.

Keywords: Common Cause Failures, Repairable Components, Distribution System.

INTRODUCTION

In general, component failures can be of two types,

- 1) Catastrophic (or) Permanent failures, and
- 2) Repairable components.

CCF [5, 12] are failures in which a single error or problem disables multiple, independent safety functions. A CCF is a dependent failure in which two or more component fault states exist within a short interval or simultaneously due to a shared cause. [13, 15, 18] CCF can occur owing to common external or internal influences. External causes may involve operational, environmental or human factors. Internal causes may involve manufacturing defects, aging effects, etc. Fault models for CCF in redundant systems are developed and techniques to design redundant systems protected against the modelled CCF are implemented [5]. Heterogeneous redundancy optimization for multi-state series-parallel systems subject to Common Cause Failures is proposed in [10]. A method for reliability modelling and assessment of a multi-state system with CCF is proposed in [11, 14].

CCF analysis of a two non-identical unit parallel system with arbitrarily distributed repair times is proposed in [1]. An expression for the Mean Time To Failure, MTTF k/n , of a

non repairable k out of n :G identical unit system with warm standby and CCF is presented in [3].

Generalized expression for MTTF of a non repairable identical unit parallel system with warm standby and CCF is developed in [2]. Time varying failure rates and Markov chain analysis are combined to obtain a hybrid reliability and availability analysis [4]. A stochastic analysis of a non identical two unit parallel system with CCF by graphical evaluation and review techniques is presented in [7].

A method for analyzing availability and reliability of repairable systems with CCF among components is proposed in [6]. Exponential asymptotic property of a parallel repairable system with CCF is explored [8]. Availability and Reliability analysis of a k -out-of- $(M+S)$: G warm standby system with repair and time varying failure rates in the presence of CCF is presented [9].

1. Objectives

In this paper, the effects of CCF are considered for 2-component repairable system with identical/Non-identical transitional rates with 4-state and 5-state models. It is extended to a 3-component repairable system which includes CCF. In this Paper, analysis with CCFs and repairable components is presented with

practical case study. Case study with Load-Node scheme has been considered in [16], the data is obtained from [17] and the analysis using cut sets is carried out in this paper. Section 1 provides the objective of the paper. Section 2 provides the proposed methodology to find the Stochastic Transitional Probability Matrix (STPM) for 2 component, 3 component repairable systems with CCF have been considered and expressions for LSP have been derived for 4 state and 5 state models. A sample power distribution network is considered in section 3 and the results are compared with components with and without CCF in section 4. Finally, the paper is concluded.

2. Proposed Methodology

2.1 System with Repairable Components and Common Cause Failures

The objective in this section is to find the LSP of the states of two component and three component systems.

2.1.1 Two Component System

Consider two component repairable system with nonidentical transition rates and non-identical capacities wherein due to CCF are occurring, the Complete State Space Diagram (CSSD) can be shown in two ways,

- 4-state model
- 5-state model

(a) 4 State Model:

The CSSD of a two component system when repairable components when CCF can occur will be shown in Figure 1 [13].

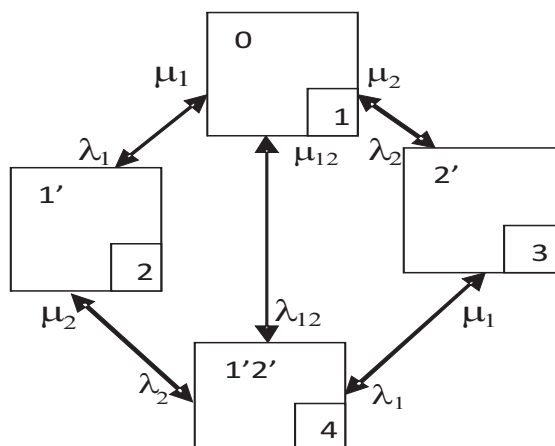


Figure 1. CSSD of a Two Component Repairable System with CCF

where λ_1, λ_2 and μ_1, μ_2 are the failure rates and repair rates of components 1 and 2 respectively. λ_{12} is the failure rate of both components 1, 2 due to common cause and μ_{12} is the repair rate of both components simultaneously so that the system can transit from state 4 to state 1 directly.

The STPM can be obtained as:

$$P = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 1 - (\lambda_1 + \lambda_2 + \lambda_{12}) & \lambda_1 & \lambda_2 & \lambda_{12} \\ 2 & \mu_1 & 1 - (\lambda_2 + \mu_1) & 0 & \lambda_2 \\ 3 & \mu_2 & 0 & 1 - (\mu_2 + \lambda_1) & \lambda_1 \\ 4 & \mu_{12} & \mu_2 & \mu_1 & 1 - (\mu_1 + \mu_2 + \mu_{12}) \end{bmatrix} \quad (1)$$

The objective will be to find the LSP of the states in Figure 1, using LSP vector approach.

Let α be the LSP vector = $[P_1 \ P_2 \ P_3 \ P_4]$

where P_1, P_2, P_3, P_4 are the LSP of states 1 to 4 respectively in Figure 1.

The solution methodology is :

$$\alpha P = \alpha$$

$$[P_1 \ P_2 \ P_3 \ P_4] \begin{bmatrix} 1 - (\lambda_1 + \lambda_2 + \lambda_{12}) & \lambda_1 & \lambda_2 & \lambda_{12} \\ \mu_1 & 1 - (\lambda_2 + \mu_1) & 0 & \lambda_2 \\ \mu_2 & 0 & 1 - (\mu_2 + \lambda_1) & \lambda_1 \\ \mu_{12} & \mu_2 & \mu_1 & 1 - (\mu_1 + \mu_2 + \mu_{12}) \end{bmatrix}$$

$$= [P_1 \ P_2 \ P_3 \ P_4] \quad (2)$$

Now expanding equation (2),

$$P_1(1 - (\lambda_1 + \lambda_2 + \lambda_{12})) + P_2\mu_1 + P_3\mu_2 + P_4\mu_{12} = P_1$$

$$P_1(\lambda_1 + \lambda_2 + \lambda_{12}) - P_2\mu_1 - P_3\mu_2 - P_4\mu_{12} = 0 \quad (3)$$

$$P_1\lambda_1 + P_2(1 - (\lambda_2 + \mu_1)) + P_4\mu_2 = P_2$$

$$-\lambda_1 P_1 + P_2(\lambda_2 + \mu_1) - \mu_2 P_4 = 0 \quad (4)$$

$$P_1\lambda_2 + P_3(1 - (\mu_2 + \lambda_1)) + P_4\mu_1 = P_3$$

$$-\lambda_2 P_1 + (\mu_2 + \lambda_1)P_3 - \mu_1 P_4 = 0 \quad (5)$$

Since the equations deduced from equation (2) will be having only three linearly independent equations and the other one shall be,

$$P_1 + P_2 + P_3 + P_4 = 1 \quad (6)$$

Writing equations (3) to (6) in matrix form,

$$\begin{bmatrix} (\lambda_1 + \lambda_2 + \lambda_{12}) & -\mu_1 & -\mu_2 & -\mu_{12} \\ -\lambda_1 & (\mu_1 + \lambda_2) & 0 & -\mu_2 \\ -\lambda_2 & 0 & (\lambda_1 + \mu_2) & -\mu_1 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} P_1 \\ P_2 \\ P_3 \\ P_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \quad (7)$$

Although in the earlier methods, Cramer's rule has been

shown to be adopted for solving P_1, P_2, P_3, P_4 , for higher number of variables, Cramer's rule becomes cumbersome and laborious. The advantage of equation (7) is that the values of LSP will be finite and lies between zero and one and therefore the set of linear algebraic equations have a unique solution. Therefore, Gauss elimination method or Gauss Jordan method can be used for solving P_1, P_2, P_3, P_4 if the data is known.

Now, if the components or units have identical capacities and identical transitional rates, Figure 1 can be reduced to Figure 2.

Now, the STPM can be written as,

$$P = \begin{matrix} & \begin{matrix} A & B & C \end{matrix} \\ \begin{matrix} A \\ B \\ C \end{matrix} & \begin{bmatrix} 1-(2\lambda+\lambda_{12}) & 2\lambda & \lambda_{12} \\ \mu & 1-(\lambda+\mu) & \lambda \\ \mu_{12} & 2\mu & 1-(2\mu+\mu_{12}) \end{bmatrix} \end{matrix} \quad (8)$$

Figure 2 shows the Merged State Space Diagram (MSSD) of a two component repairable system with CCF.

The objective will be to find the LSP of the states in Figure 2 using LSP vector approach.

Let α be the LSP vector = $[P_A \ P_B \ P_C]$,

where P_A, P_B, P_C are the LSP of states A to C respectively in Figure 2.

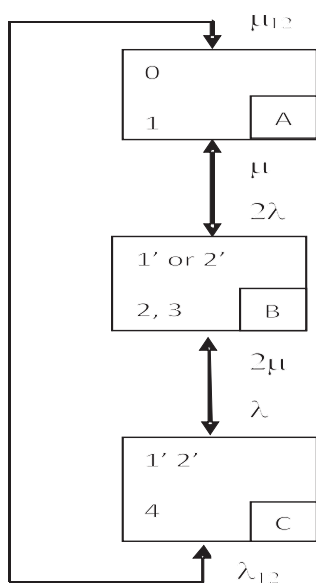


Figure 2. Merged State Space Diagram (MSSD) of a Two Component Repairable System with CCF

Now the solution methodology is,

$$\alpha P = \alpha$$

$$[P_A \ P_B \ P_C] \begin{bmatrix} 1-(2\lambda+\lambda_{12}) & 2\lambda & \lambda_{12} \\ \mu & 1-(\lambda+\mu) & \lambda \\ \mu_{12} & 2\mu & 1-(2\mu+\mu_{12}) \end{bmatrix} = [P_A \ P_B \ P_C] \quad (9)$$

Now expanding equation (9),

$$P_A(1-(2\lambda+\lambda_{12}))+\mu P_B+\mu_{12}P_C=P_A$$

$$P_A(2\lambda+\lambda_{12})-\mu P_B-\mu_{12}P_C=0 \quad (10)$$

$$P_A 2\lambda+P_B(1-(\lambda+\mu))+2\mu P_C=P_B$$

$$-2\lambda P_A+P_B(\lambda+\mu)-2\mu P_C=0 \quad (11)$$

and the other equation will be:

$$P_A+P_B+P_C=1 \quad (12)$$

Writing equations (10) to (12) in matrix form

$$\begin{bmatrix} 2\lambda+\lambda_{12} & -\mu & -\mu_{12} \\ -2\lambda & \lambda+\mu & -2\mu \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} P_A \\ P_B \\ P_C \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad (13)$$

Solving equation (13) using Cramer's rule,

$$P_A = \frac{1}{\Delta} \begin{vmatrix} 0 & -\mu & -\mu_{12} \\ 0 & \lambda+\mu & -2\mu \\ 1 & 1 & 1 \end{vmatrix}$$

$$\text{where } \Delta = \begin{vmatrix} 2\lambda+\lambda_{12} & -\mu & -\mu_{12} \\ -2\lambda & \lambda+\mu & -2\mu \\ 1 & 1 & 1 \end{vmatrix}$$

$$= 2(\lambda+\mu)^2 + \lambda_{12}(\lambda+3\mu) + \mu_{12}(3\lambda+\mu)$$

$$\therefore P_A = \frac{2\mu^2 + \mu_{12}(\lambda+\mu)}{2(\lambda+\mu)^2 + \lambda_{12}(\lambda+3\mu) + \mu_{12}(3\lambda+\mu)} \quad (14)$$

$$\text{Now } P_B = \frac{1}{\Delta} \begin{vmatrix} 2\lambda+\lambda_{12} & 0 & -\mu_{12} \\ -2\lambda & 0 & -2\mu \\ 1 & 1 & 1 \end{vmatrix}$$

$$= \frac{4\lambda\mu + \lambda_{12} \cdot 2\mu + \mu_{12} \cdot 2\lambda}{2(\lambda+\mu)^2 + \lambda_{12}(\lambda+3\mu) + \mu_{12}(3\lambda+\mu)} \quad (15)$$

$$\text{Now } P_C = \frac{1}{\Delta} \begin{vmatrix} 2\lambda+\lambda_{12} & -\mu & 0 \\ -2\lambda & \lambda+\mu & 0 \\ 1 & 1 & 1 \end{vmatrix}$$

$$= \frac{2\lambda^2 + \lambda_{12}(\mu + \lambda)}{2(\lambda + \mu)^2 + \lambda_{12}(\lambda + 3\mu) + \mu_{12}(3\lambda + \mu)} \quad (16)$$

Now, the equivalent failure rate of the components including CCF for 4 state model can be expressed as [13],

$$\lambda_{CCF} = \lambda_1\lambda_2(r_1 + r_2) + \lambda_{12} \quad (17)$$

The mean outage time can be expressed as,

$$r_{CCF} = \frac{r_1 r_2 \lambda_{12}}{r_1 r_2 + r_1 \lambda_{12} + r_2 \lambda_{12}} \quad (18)$$

The average annual outage time can be expressed as,

$$U_{CCF} = \lambda_{CCF} r_{CCF} \quad (19)$$

(b) 5 - State Model:

The CSSD of a two component system when repairable components due to CCF can occur with 5 –state model is shown in Figure 3 [13].

The STPM can be obtained from Figure 3 as:

$$P = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 & 5 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} & \begin{bmatrix} 1-(\lambda_1+\lambda_2+\lambda_{12}) & \lambda_1 & \lambda_2 & 0 & \lambda_{12} \\ \mu_1 & 1-(\mu_1+\lambda_2) & 0 & \lambda_2 & 0 \\ \mu_2 & 0 & 1-(\lambda_1+\mu_2) & \lambda_1 & 0 \\ 0 & \mu_2 & \mu_1 & 1-(\mu_1+\mu_2) & 0 \\ \mu_{12} & 0 & 0 & 0 & 1-(\mu_{12}) \end{bmatrix} \end{matrix} \quad (20)$$

Now, the objective will be to find the LSP of the states 1 to 5 in Figure 3, using LSP vector approach.

Let α be the LSP vector = $[P_1 P_2 P_3 P_4 P_5]$

where, P_i , $i = 1$ to 5, is the LSP of state 'i'.

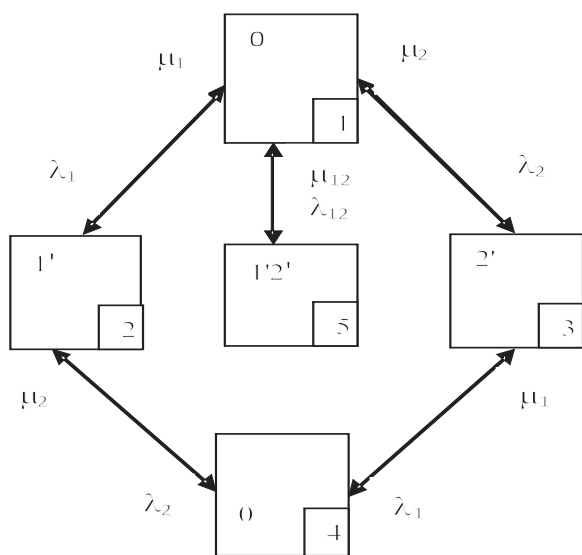


Figure 3. CSSD of a Two Component Repairable System with CCF as 5-state Model

Figure 3 shows the CSSD of a two component repairable system with CCF as 5-state model

The solution methodology is: $\alpha P = \alpha$

$[P_1 P_2 P_3 P_4 P_5]$.

$$\begin{bmatrix} 1-(\lambda_1+\lambda_2+\lambda_{12}) & \lambda_1 & \lambda_2 & 0 & \lambda_{12} \\ \mu_1 & 1-(\mu_1+\lambda_2) & 0 & \lambda_2 & 0 \\ \mu_2 & 0 & 1-(\lambda_1+\mu_2) & \lambda_1 & 0 \\ 0 & \mu_2 & \mu_1 & 1-(\mu_1+\mu_2) & 0 \\ \mu_{12} & 0 & 0 & 0 & 1-(\mu_{12}) \end{bmatrix} \quad (21)$$

$= [P_1 P_2 P_3 P_4 P_5]$

Now expanding Equation (21),

$$[1-(\lambda_1+\lambda_2+\lambda_{12})]P_1 + \mu_1 P_2 + \mu_2 P_3 + \mu_{12} P_5 = P_1$$

$$(\lambda_1 + \lambda_2 + \lambda_{12})P_1 - \mu_1 P_2 - \mu_2 P_3 - \mu_{12} P_5 = 0 \quad (22)$$

$$\lambda_1 P_1 + [1-(\mu_1 + \lambda_2)]P_2 + \mu_2 P_4 = P_2 \quad (23)$$

$$-\lambda_1 P_1 + (\mu_1 + \lambda_2)P_2 - \mu_2 P_4 = 0 \quad (23)$$

$$\lambda_2 P_1 + [1-(\lambda_1 + \mu_2)]P_3 + \mu_1 P_4 = P_3 \quad (24)$$

$$-\lambda_2 P_1 + (\lambda_1 + \mu_2)P_3 - \mu_1 P_4 = 0 \quad (24)$$

$$\lambda_2 P_2 + \lambda_1 P_3 + [1-(\mu_1 + \mu_2)]P_4 = P_4 \quad (25)$$

$$-\lambda_2 P_2 - \lambda_1 P_3 + (\mu_1 + \mu_2)P_4 = 0 \quad (25)$$

Since the equations deduced from equation (21) will be having only four linearly independent equations and the other one shall be,

$$P_1 + P_2 + P_3 + P_4 + P_5 = 1. \quad (26)$$

Now writing equations (22) to (26) in matrix form,

$$\begin{bmatrix} \lambda_1 + \lambda_2 + \lambda_{12} & -\mu_1 & -\mu_2 & 0 & -\mu_{12} \\ \lambda_1 & \mu_1 + \lambda_2 & 0 & \mu_2 & 0 \\ -\lambda_2 & 0 & \lambda_1 + \mu_2 & -\mu_1 & 0 \\ 0 & -\lambda_2 & -\lambda_1 & \mu_1 + \mu_2 & 0 \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} P_1 \\ P_2 \\ P_3 \\ P_4 \\ P_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \quad (27)$$

As stated in the previous section, Gauss - elimination method or Gauss - Jordan method can be used for solving P_1, P_2, P_3, P_4 and P_5 .

Now the equivalent failure rate of the components including CCF for 5 state model can be expressed as [13],

$$\lambda_{CCF} = \lambda_1\lambda_2(r_1 + r_2) + \lambda_{12} \quad (28)$$

The mean outage time can be expressed as,

$$r_{CCF} = \frac{\lambda_1\lambda_2 r_1 r_2 + \lambda_{12} r_1 r_2}{\lambda_1\lambda_2(r_1 + r_2) + \lambda_{12}} \quad (29)$$

The average annual outage time can be expressed as,

$$U_{CCF} = \lambda_{CCF} \cdot r_{CCF} = \lambda_1 \lambda_2 r_1 r_2 + \lambda_{12} r_{12} \quad (30)$$

For example, consider that there are two components in a system having failure rates of 0.125 f/yr, 0.2 f/yr respectively, and repair times of 14 hrs and 12 hrs respectively. The failure rate and repair time due to CCF of the components will be 0.1 f/yr and 20 hrs respectively. The Basic Probability Indices for the system can be calculated as follows,

- With no CCF
- With CCF of 4 state model
- With CCF of 5 state model

i) With no CCF:

$$\lambda_1 = 0.125 \text{ f/yr}; \lambda_2 = 0.2 \text{ f/yr}; \lambda_{12} = 0; r_{12} = 0$$

$$r_1 = 14 \text{ hrs}; r_2 = 12 \text{ hrs}$$

The equivalent failure rate of the system is,

$$\lambda_p = \lambda_1 \lambda_2 (r_1 + r_2) = 7.42 * 10^{-5} \text{ f/yr}$$

The mean outage time of the system is,

$$r_p = \frac{r_1 r_2}{r_1 + r_2} = 6.42 \text{ hrs}$$

The average annual outage time is,

$$U_p = \lambda_p r_p = 4.79 * 10^{-4} \text{ hrs/yr} = 1.72 \text{ sec}$$

ii) With CCF of 4 State Model

$$\text{Here } \lambda_{12} = 0.1 \text{ f/yr}; r_{12} = 20 \text{ hrs}$$

$$\lambda_{CCF} = \lambda_1 \lambda_2 (r_1 + r_2) + \lambda_{12} = 0.1 \text{ f/yr}$$

$$r_{CCF} = \frac{r_1 r_2 r_{12}}{r_1 r_2 + r_1 r_{12} + r_2 r_{12}} = 4.88 \text{ hrs}$$

$$U_{CCF} = \lambda_{CCF} \cdot r_{CCF} = 0.488 \text{ hrs/yr}$$

iii) With CCF of 5 State Model

$$\lambda_{CCF} = \lambda_1 \lambda_2 (r_1 + r_2) + \lambda_{12} = 0.1 \text{ f/yr}$$

$$r_{CCF} = \frac{\lambda_1 \lambda_2 r_1 r_2 + \lambda_{12} r_{12}}{\lambda_1 \lambda_2 (r_1 + r_2) + \lambda_{12}} = 62 \text{ hrs}$$

$$U_{CCF} = \lambda_{CCF} \cdot r_{CCF} = 6.2 \text{ hrs/yr}$$

2.1.2 Three Component System

Figure 4 shows the CSSD of a three component repairable system with CCF as 8-state model. Consider three component repairable system with non-identical

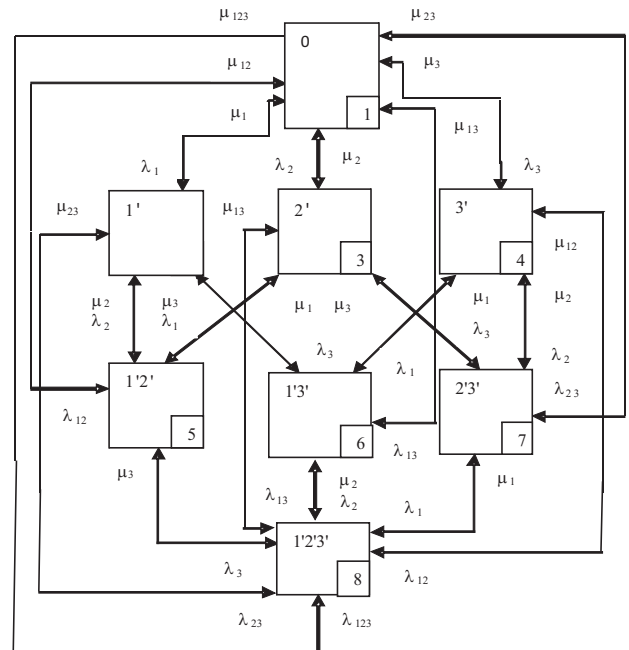


Figure 4. CSSD of a Three Component Repairable System with CCF as 8-state Model

transition rates and non-identical capacities wherein due to CCF are occurring, the CSSD can be shown in Figure 4 with 8 – state model.

If the components or units have identical capacities, then Figure 4 can be reduced to 4 state model if the states 2, 3, 4 and 5, 6, 7 are merged as shown in Figure 5, and let $\lambda_1 = \lambda_2 = \lambda_3 = \lambda$; $\mu_1 = \mu_2 = \mu_3 = \mu$.

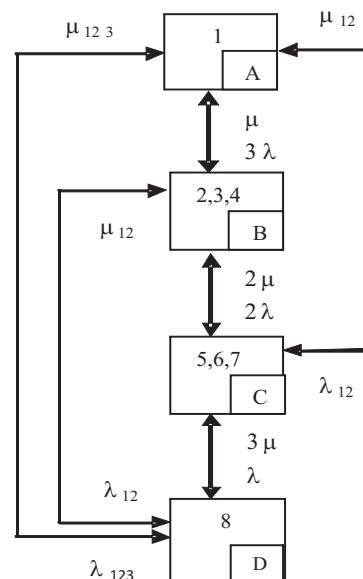


Figure 5. MSSD of a Three Component Repairable System with CCF having Identical Capacities and Transition Rates

The STPM can be obtained from Figure 5 as,

$$P = \begin{bmatrix} A & B & C & D \\ A \left[\begin{array}{cccc} 1-(3\lambda+3\lambda_{12}+\lambda_{123}) & 3\lambda & 3\lambda_{12} & \lambda_{123} \\ \mu & 1-(\mu+2\lambda+3\lambda_{12}) & 2\lambda & 3\lambda_{12} \\ 3\mu_{12} & 2\mu & 1-(2\mu+\lambda+3\mu_{12}) & \lambda \\ \mu_{123} & 3\mu_{12} & 3\mu & 1-(3\mu+3\mu_{12}+\mu_{123}) \end{array} \right] \end{bmatrix} \quad (31)$$

Now, the objective will be to find the LSP of the states A, B, C and D in Figure 5.

Let α be the LSP vector = $[P_A P_B P_C P_D]$

where $P_i \forall i = A \text{ to } D$, is the LSP of state 'i'

Now the solution methodology is : $\alpha P = \alpha$

$[P_A P_B P_C P_D]$.

$$\begin{bmatrix} 1-(3\lambda+3\lambda_{12}+\lambda_{123}) & 3\lambda & 3\lambda_{12} & \lambda_{123} \\ \mu & 1-(\mu+2\lambda+3\lambda_{12}) & 2\lambda & 3\lambda_{12} \\ 3\mu_{12} & 2\mu & 1-(2\mu+\lambda+3\mu_{12}) & \lambda \\ \mu_{123} & 3\mu_{12} & 3\mu & 1-(3\mu+3\mu_{12}+\mu_{123}) \end{bmatrix} \quad (32)$$

$= [P_A P_B P_C P_D]$

Now expanding equation (32),

$$P_A [1-(3\lambda+3\lambda_{12}+\lambda_{123})] + P_B \mu + P_C 3\mu_{12} + P_D \mu_{123} = P_A \quad (33)$$

$$P_A (3\lambda+3\lambda_{12}+\lambda_{123}) - P_B \mu - P_C 3\mu_{12} - P_D \mu_{123} = 0 \quad (34)$$

$$P_A 3\lambda + P_B [1-(\mu+2\lambda+3\lambda_{12})] + P_C 2\mu + P_D 3\mu_{12} = P_B \quad (35)$$

Since the equations deduced from equation (32) will be having only three linearly independent equations and the other one shall be,

$$P_A + P_B + P_C + P_D = 1 \quad (36)$$

Writing equations (33) to (36) in matrix form,

$$\begin{bmatrix} 3\lambda+3\lambda_{12}+\lambda_{123} & -\mu & -3\mu_{12} & -\mu_{123} \\ -3\lambda & \mu+2\lambda+3\lambda_{12} & -2\lambda & -3\lambda_{12} \\ -3\mu_{12} & -2\mu & 2\mu+\lambda+3\mu_{12} & -\lambda \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} P_A \\ P_B \\ P_C \\ P_D \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \quad (37)$$

As stated in the previous section, Gauss - elimination method or Gauss - Jordan method can be used for solving P_A, P_B, P_C and P_D .

3. Case study

The Load Node scheme is shown in Figure 6. Two fully redundant HV/MV transformer bays feed the two relevant MV bus-bars. The components considered are Circuit

Breakers, Transformers, and Feeders. It has to be stated that, the Circuit Breaker duty is to clear faults on other equipment, but itself can be subject to fault. It can also be stated that, there is a possibility of CCF in case of a failure on a transformer, due to the possible overload of the other transformer. It is considered that the failure modes of the first failure and CCF are different. The first failure can be an internal fault, conversely the CCF is due to an overload that can be caused by a design under-sizing. Failure and repair times of Load Node scheme are given in Table 1 [16,17].

The Reliability Logic Diagrams (RLD) for load groups L_1, L_2 and Load Node scheme using cut sets are shown in Figures 7 and 8 respectively.

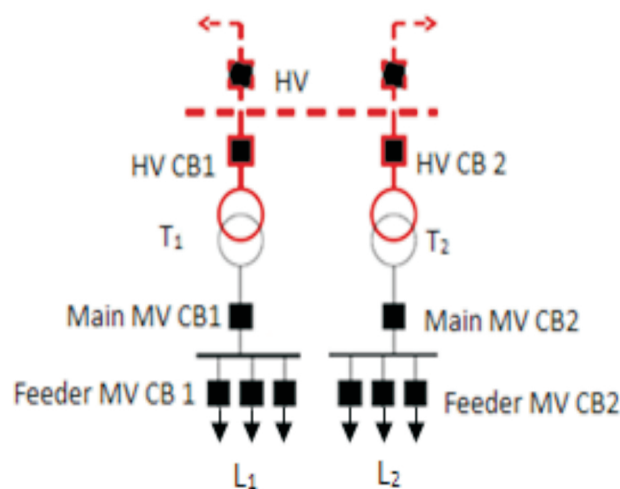


Figure 6. Load Node Scheme

Component	Failure rate (/Yr)	Average Repair time (hrs)
HVCB1	0.34	1
HVCB2	0.34	1
Transformer 1 (T1)	0.049	48
Transformer 2 (T2)	0.049	48
Transformer CCF	0.1	48
Main Middle Voltage CB1 (MMVCB1)	0.34	1
Main Middle Voltage CB2 (MMVCB2)	0.34	1
Feeder 1 (F1)	0.25	1
Feeder 2 (F2)	0.25	1
Feeder MV CB1 (FMVCB1)	0.34	1
Feeder MV CB2 (FMVCB2)	0.34	1

Table 1. Failure and Repair Times of Load-Node Scheme

4. Results and Analysis

4.1 Basic Probability Indices without CCF

The Basic Probability Indices (BPI) of Load group 1 (L_1) without CCF are obtained as,

$$\lambda_{L1} = \lambda_{HVCB1} + \lambda_{TF1} + \lambda_{MMVCB1} + \lambda_{F1} + \lambda_{FMVCB1}$$

$$= 1.319 \text{ f/yr} \quad (38)$$

$$r_{L1} = (\lambda_{HVCB1} r_{HVCB1} + \lambda_{TF1} r_{TF1} + \lambda_{MMVCB1} r_{MMVCB1} + \lambda_{F1} r_{F1} + \lambda_{FMVCB1} r_{FMVCB1}) / \lambda_{L1} = 2.746 \text{ hrs} \quad (39)$$

$$U_{L1} = \lambda_{L1} r_{L1} = 3.622 \text{ hrs/yr} \quad (40)$$

As identical components are considered, the BPI of Load group 2 (L_2) without CCF are given as,

$$\lambda_{L2} = \lambda_{L1} = 1.319 \text{ f/yr} \quad (41)$$

$$r_{L2} = r_{L1} = 2.746 \text{ hrs} \quad (42)$$

$$U_{L2} = U_{L1} = 3.622 \text{ hrs/yr} \quad (43)$$

The BPI of Load-Node scheme without CCF are obtained as,

$$\lambda_S = \lambda_{L1} + \lambda_{L2} = 1.319 + 1.319 = 2.638 \text{ f/yr} \quad (44)$$

$$r_S = (\lambda_{L1} r_{L1} + \lambda_{L2} r_{L2}) / \lambda_S = 2.746 \text{ hrs} \quad (45)$$

$$U_S = \lambda_S r_S = 7.244 \text{ hrs/yr} \quad (46)$$

3.2 Basic Probability Indices with CCF

The BPI of Load group 1 (L_1) with CCF are obtained as,

$$\lambda_{L1CCF} = \lambda_{HVCB1} + \lambda_{TF1} + \lambda_{CCF1} + \lambda_{MMVCB1} + \lambda_{F1} + \lambda_{FMVCB1} = 1.419 \text{ f/yr} \quad (47)$$

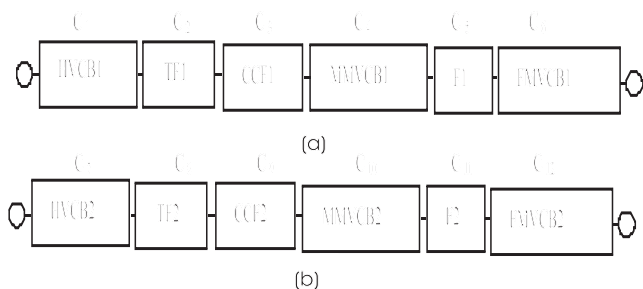


Figure 7. RLD for (a) Load Group L_1 , (b) Load Group L_2

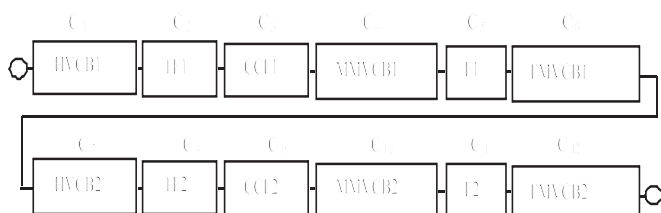


Figure 8. RLD of Load-Node Scheme using Cut sets

Parameter/unit	Without CCF	With CCF
λ_{L1}	1.319	1.419
U_{L1}	3.622	8.422
r_{L1} (hrs)	2.746	5.935
r_{L2} (hrs)	2.746	5.935
λ_S	2.638	2.838
r_S (hrs)	2.746	5.935
U_S (hrs/yr)	7.244	16.844

Table 2. Basic Probability Indices with and without CCF

$$r_{L1CCF} = (\lambda_{HVCB1} r_{HVCB1} + \lambda_{TF1} r_{TF1} + \lambda_{CCF1} r_{CCF1} + \lambda_{MMVCB1} r_{MMVCB1} + \lambda_{F1} r_{F1} + \lambda_{FMVCB1} r_{FMVCB1}) / \lambda_{L1CCF} = 5.935 \text{ hrs} \quad (48)$$

$$U_{L1CCF} = \lambda_{L1CCF} r_{L1CCF} = 8.422 \text{ hrs/yr} \quad (49)$$

As identical components are considered, the BPI of Load group 2 (L_2) with CCF are given as,

$$\lambda_{L2CCF} = \lambda_{L1CCF} = 1.419 \text{ f/yr} \quad (50)$$

$$r_{L2CCF} = r_{L1CCF} = 5.935 \text{ hrs} \quad (51)$$

$$U_{L2CCF} = U_{L1CCF} = 8.422 \text{ hrs/yr} \quad (52)$$

The BPI of Load-Node scheme with CCF are obtained as,

$$\lambda_{SCCF} = \lambda_{L1CCF} + \lambda_{L2CCF} = 2.838 \text{ f/yr} \quad (53)$$

$$r_{SCCF} = (\lambda_{L1CCF} r_{L1CCF} + \lambda_{L2CCF} r_{L2CCF}) / \lambda_{SCCF} = 5.935 \text{ hrs} \quad (54)$$

$$U_{SCCF} = \lambda_{SCCF} r_{SCCF} = 16.844 \text{ hrs/yr} \quad (55)$$

Thus, the BPI obtained with and without CCF are presented in Table 2. From Table 2, it can be observed that equivalent failure rate, repair time and average annual outage time will increase with CCF for Load groups L_1 , L_2 and for the system as well.

Conclusion

In this paper, the concept of Common Cause Failures has been discussed. For repairable components, the analysis using CCF has been dealt by considering two component and three component repairable models. It can also be extended to nine state model of a three component system. A study is carried out on a power distribution network, and the results are presented for the component

probabilities with and without CCF. It is concluded that, all the Basic Probability Indices will be increased with increase in Common Cause Failure rates of the components in the system and from the feeder to the corresponding load points also.

References

- [1]. B.S. Dhillon, and O.C. Anude (1993). "Common Cause Failure analysis of a non-identical unit parallel system with arbitrarily distributed repair times". *Journal of Microelectronics Reliability*, Vol. 33, No.1, pp. 87-103.
- [2]. B.S. Dhillon, and O.C. Anude (1993). "Common Cause Failure analysis of a redundant system with non-repairable units". *Journal of Microelectronics Reliability*, Vol. 33, No.10, pp. 1499-1509.
- [3]. B.S. Dhillon, and O.C. Anude (1994). "Common Cause Failure Analysis of a k-out-of-n:G system with repairable units". *Journal of Microelectronics Reliability*, Vol. 34, No.3, pp. 429-442.
- [4]. Hassett, T.F. Dietrich, and Duane L, (1995). "Time varying failure rates in the availability and reliability analysis of repairable systems". *IEEE Trans. on Reliability*, Vol. 44, No.1, pp.155-160.
- [5]. Subhashish Mitra, and Edward J.McCluskey (2000). "Design of Redundant Systems Protected Against CMF". *Center for Reliable Computing*, pp. 1-24.
- [6]. T. Zhang, and M. Horigome, (2001). "Availability and reliability of system with dependent components and time-varying failure and repair rates". *IEEE Trans. on Reliability*, Vol.50, No.2, pp. 151-158.
- [7]. Sridharan V, and T.V. Kalyani (2002). "Stochastic analysis of a non-identical two-unit parallel system with CCF using GERT technique". *International Journal of Information and Management Sciences*, Vol.13, No.1, pp. 49-57.
- [8]. Shen, Z., and Fan. W., (2008). "Exponential asymptotic property of a parallel repairable system with warm standby under Common-Cause Failure". *Journal of Mathematical Analysis and Applications*, Vol. 341, No.1, pp. 457-466.
- [9]. M. A. El-Damcese (2009). "Analysis of Warm Standby Systems Subject to Common-Cause Failures with Time Varying Failure and Repair Rates". *Applied Mathematical Sciences*, Vol. 3, No.18, pp. 853-860.
- [10]. Li, C-Y., Chen, X., Yi, X-S., and Tao, J-Y., (2010). "Heterogeneous redundancy optimization for multi-state series-parallel systems subject to Common Cause Failures". *Reliability Engineering and System Safety*, Vol. 95, No.3, pp. 202-207.
- [11]. Mi J, Li Y, Huang H-Z, Liu Y, and Zhang X-L., (2013). "Reliability analysis of multi-state system with Common Cause Failure based on bayesian networks". *Maintenance and Reliability*, Vol.15, No.2, pp. 169-175.
- [12]. D. Ravi Kumar, P. Srinivasa Varma, and V. Sankar (2014). "Approximate System Reliability analysis of systems with Catastrophic and CMF". *Elsevier, 38th National System Conference on Real Time Systems: Modelling Analysis and Control*, pp. 108-113.
- [13]. R. Billinton, and R. N. Allan (2007). *Reliability Evaluation of Engineering Systems*, Second Edition. Springer International Edition, Reprinted in India, BS Publications, pp. 352-359.
- [14]. P. Hokstad, M. Rausand (2008). *Common Cause Failure Modeling: Status and Trends-Handbook of Performability Engineering*, Edited by K.B. Misra Springer, London.
- [15]. V. Sankar, (2015). *System Reliability Concepts*. Himalaya Publishing House, pp. 239-275.
- [16]. Giancarlo Guenzi, (2010). "Reliability evaluation of Common-Cause failures and other interdependencies in large reconfigurable networks". Ph.D.Dissertation, University of Maryland, USA, pp. 58-75.
- [17]. MIL-HDBK-217E, (1991). *On Reliability Prediction of Electronic Equipment*. Department of Defense, Washington DC.
- [18]. NEA, (2004). *International Common Cause Failure Data Exchange*. ICDE general coding guidelines. Technical note EA/CSNI/R4. Nuclear Energy Agency.

ABOUT THE AUTHORS

D. Ravi Kumar is currently working as an Assistant Professor in the Department of Electrical and Electronics Engineering at VNR Vignana Jyothi Institute of Engineering and Technology, Hyderabad, India and is pursuing Ph.D in JNTU Anantapur, India. He completed his B. Tech in Electrical and Electronics Engineering from J.N.T.U, Hyderabad, India and M. Tech in Power Systems from J.N.T.U, Anantapur, India. He is a Life Member of Indian Society for Technical Education (ISTE). He has published 12 papers in various International/National Journals/Conferences. He has presented a paper in IEEE International Conference ICBEST-2015 at CREATE, Singapore. His areas of interest are Power Systems, Reliability Engineering, Reliability Optimization and Deregulation.



V. Sankar is currently working as a Professor in the Department of Electrical and Electronics Engineering, and Director of Foreign Affairs and Alumni matters, JNTUA, Andhra Pradesh, India. He has obtained his B.Tech (EEE) Degree, M.Tech (Power Systems) and Ph.D (Power System Reliability). He is a recipient of A.P. State Best Teacher Award on 5th September 2010. He is a Senior Member of IEEE. He has served as a Coordinator of IEEE Student Activities, Ananthapuramu Zone of Andhra Pradesh (AZAP) from April 2014 to January 2016. He is a member of Academic Senate of Krishna University, Machilipatnam. He has authored a text book entitled 'System Reliability Concepts' published by Himalaya Publishing House in 2015. He is an Executive group member of A.P Knowledge Mission. Presently he is a Chairman of IEEE Student activities centre of AZAP. He is a Coordinator of APRUSA of JNTUA. He has published 89 papers in various International/National Journals/Conferences. His areas of interest are Power Systems, and Reliability Engineering.

